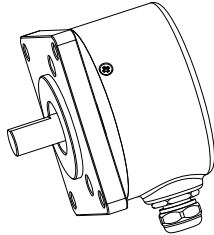


S50F

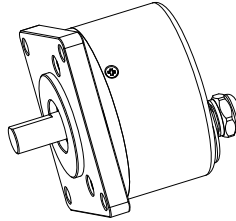
Specifications 1/6

Incremental Type (Solid shaft,flange)

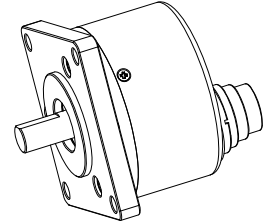
- Feature: easy to install with flange,optional various output mode,long service life,etc
- Application: textile industry、 packing machinery、 production line,etc,for automation control
- External dimensions: external diameter $\phi 50\text{mm}$,thickness 35.7mm,diameter of shaft 8mm(D type)
- Resolution: up to 23040P/R
- Supply voltage: DC5V; DC8-30V
- Protection: IP50; IP65
- Cable length: 1000mm
- Weight: about 220g



S50F-T



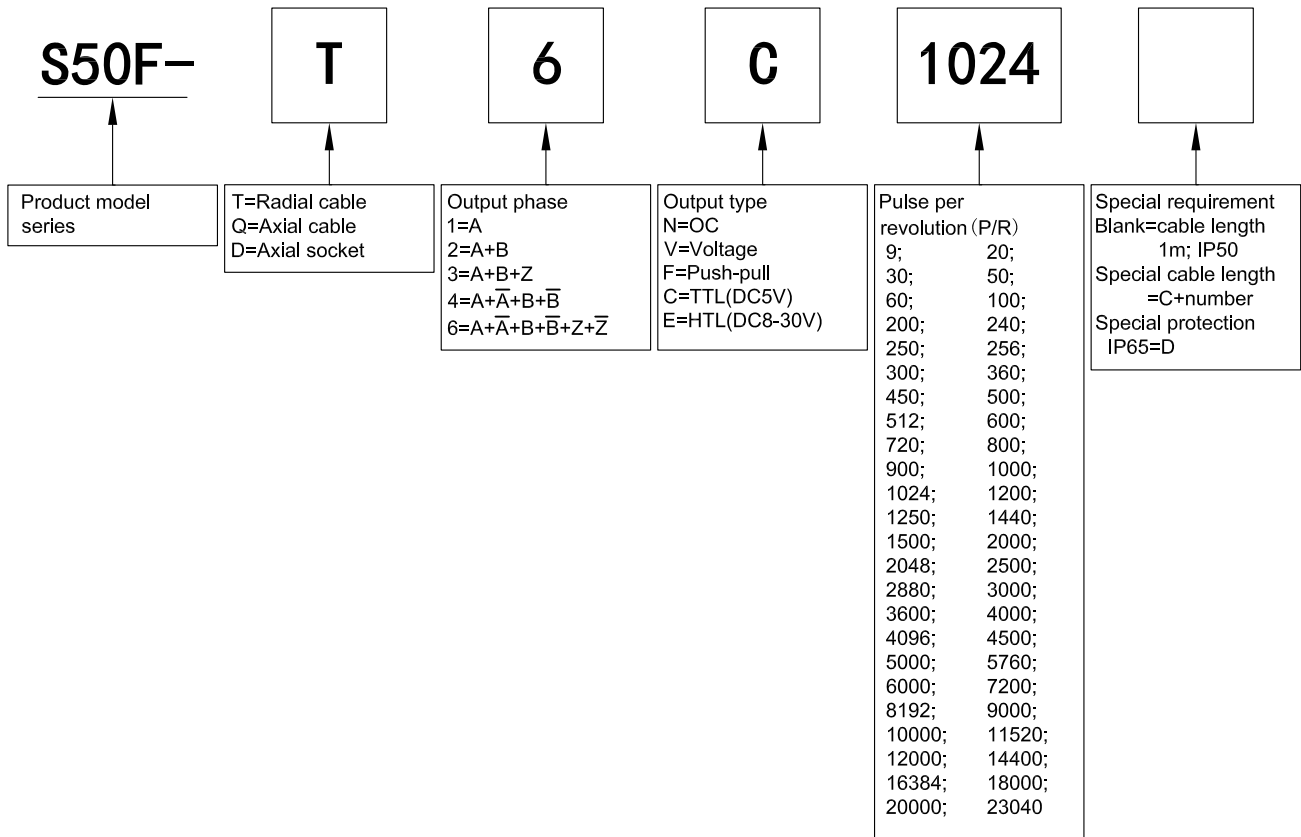
S50F-Q



S50F-D

Model Guide

- Model form (filled required parameters in the box as following)
- Must choose supply voltage: DC5V; DC8-30V
- If need coupling, please purchase additionally (Please refer to accessory at specifications 5/5)



S50F

Specifications 2/6

Output Mode

Output type	Output circuit	Output wave form	Connection
OC		<p> $a.b.c.d = \frac{T}{4} \pm \frac{T}{8}$ Phase A is ahead of B by $\frac{T}{4} \pm \frac{T}{8}$, rotation direction CW (Viewing from shaft end, direction is clockwise rotation) CW direction \rightarrow </p>	0=GND 1=red=DC5V; DC8-30V 2=black=OV 3=white=A 4=green=B 5=yellow=Z
Push-Pull		<p> $a.b.c.d = \frac{T}{4} \pm \frac{T}{8}$ Phase A is ahead of B by $\frac{T}{4} \pm \frac{T}{8}$, rotation direction CW (Viewing from shaft end, direction is clockwise rotation) CW direction \rightarrow </p>	
Voltage		<p> $a.b.c.d = \frac{T}{4} \pm \frac{T}{8}$ Phase A is ahead of B by $\frac{T}{4} \pm \frac{T}{8}$, rotation direction CW (Viewing from shaft end, direction is clockwise rotation) CW direction \rightarrow </p>	
TTL		<p> $a.b.c.d = \frac{T}{4} \pm \frac{T}{8}$ Phase A is ahead of B by $\frac{T}{4} \pm \frac{T}{8}$, rotation direction CW (Viewing from shaft end, direction is clockwise rotation) CW direction \rightarrow </p>	0=shielding=GND 1=red=DC5V; DC8-30V 2=black=OV 3=white=A 4=green=B 5=yellow=Z 6=white/black= \bar{A} 7=green/black= \bar{B} 8=yellow/black= \bar{Z}
HTL		<p> $\frac{T}{4} \pm \frac{T}{8}$ CW direction \rightarrow </p>	

■ Electrical Characteristics

Parameter Item	Output type	OC		Voltage		Push-pull		TTL		HTL		
Supply voltage		DC+5V±5%; DC8V-30V±5%						DC+5V±5%		DC8-30V±5%		
Consumption current		100mA Max										
Allowable ripple		≤3%rms										
Top response frequency		100KHz						200KHz		300KHz		
Output capacity	Output current	Input	≤30mA		Load resistance 2.2K	≤30mA		≤±20mA		≤±50mA		
		Output	—			≤10mA						
	Output voltage	"H"	—		—		≥[(Supply voltage)-2.5V]		≥2.5V		≥V _{CC} -3 V _{DC}	
		"L"	≤0.4V		≤0.7V(less than 20mA)		≤0.4V(30mA)		≤0.5V		≤1V V _{DC}	
	Load voltage	≤DC30V		—		—		—		—		
Rise & Fall time		Less than 2us(cable length: 2m)						Less than 1us (Cable length: 2m)		≤100ns		
Insulation strength		AC500V 60s										
Insulation resistance		10MΩ										
Mark to space ratio		45% to 55%										
Phase shift between A & B		90°±10° (frequency in low speed)										
		90°±20° (frequency in high speed)										
Origin motion		Low level available		High level available		Low level available		—				
GND		not connect to encoder										

■ Mechanical Characteristics

Shaft	∅8mm D type(stainless steel)
Starting torque	Less than 5×10^{-3} N·m
Inertia moment	Less than 3×10^{-6} kg·m ²
Shaft load	Radial 40N; Axial 20N
Slew speed	≤5000 rpm; IP65≤3000 rpm
Bearing Life	1.5×10^9 revs at rated load(100000hrs at 2500RPM)
Shell	Aluminium alloy
Weight	about 220g

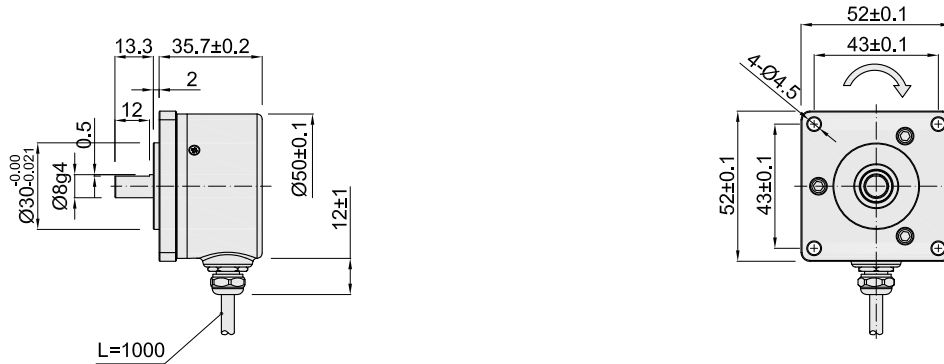
■ Environmental Specifications

Environmental temperature	Operating: -20~+80°C(repeatable winding cable: -10°C); Storage: -25~+85°C
Environmental humidity	Operating and storage: 35~85%RH(noncondensing)
Vibration(endure)	Amplitude 0.75mm,5~55Hz,2h for X,Y,Z direction individually
Shock(endure)	490m/s ² 11ms three times for X,Y,Z direction individually
Protection	IP50; IP65

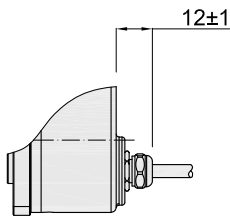
S50F Specifications 4/6

■ Basic Dimensions

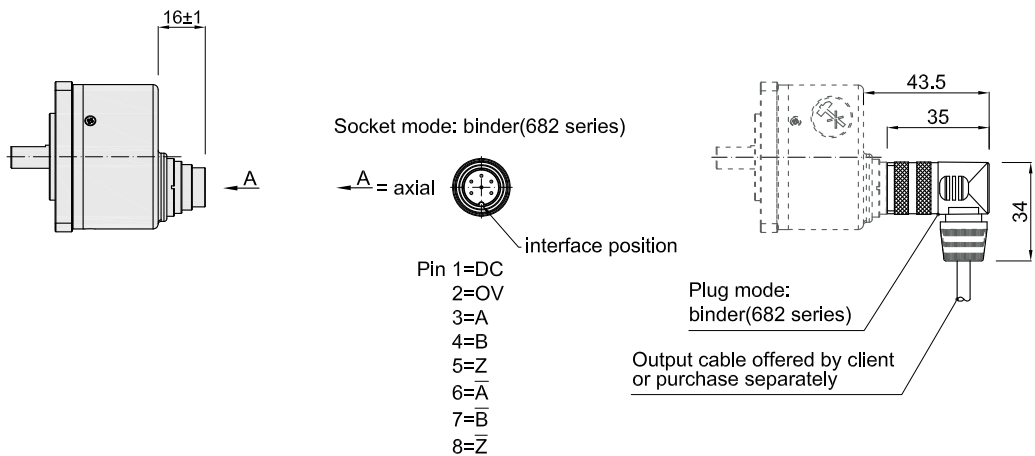
- S50F-T



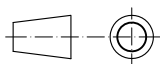
- S50F-Q



- S50F-D

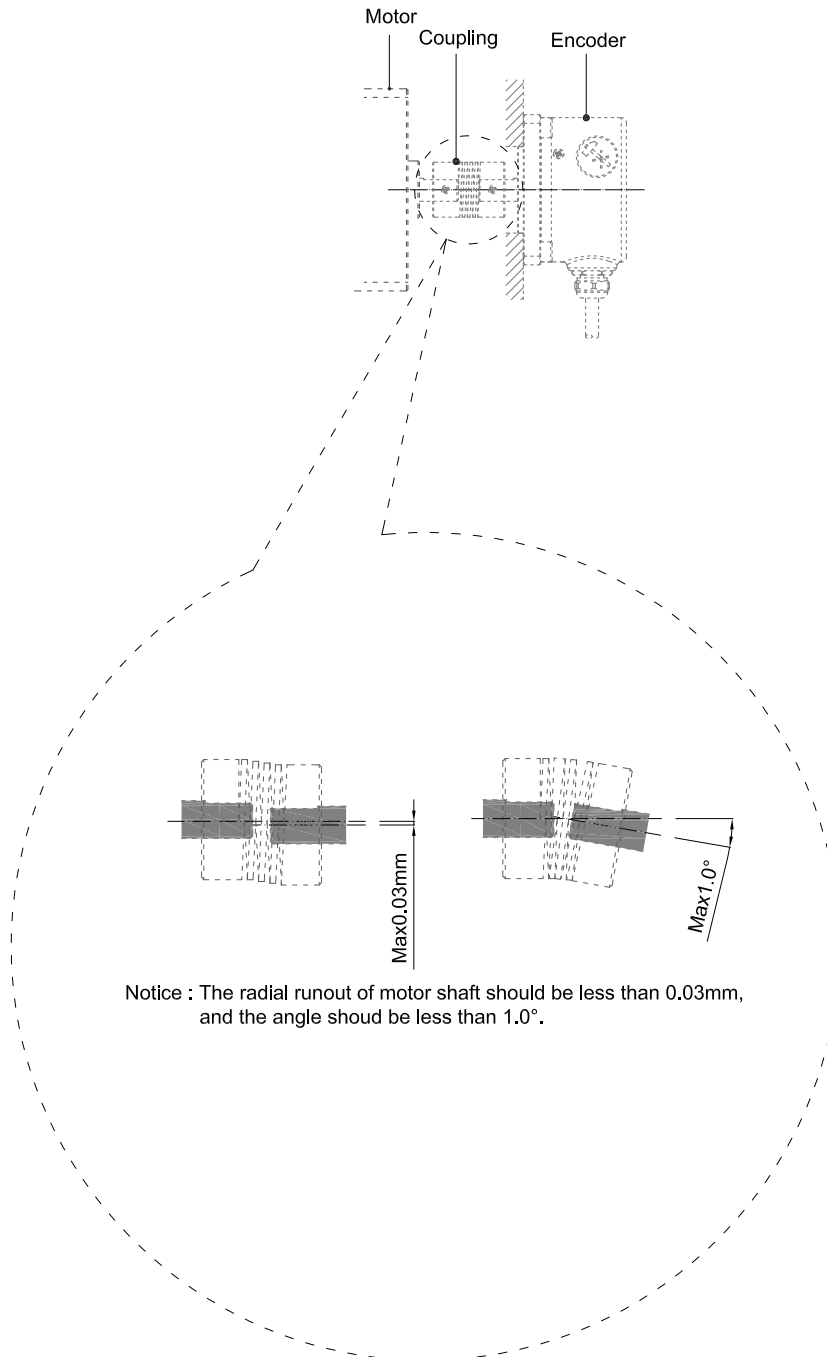


Unit: mm



= Rotate direction of signal output shaft

■ Assembling requirement


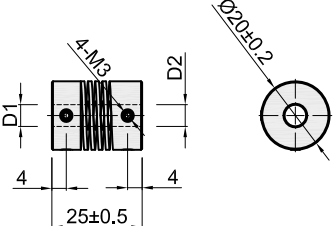

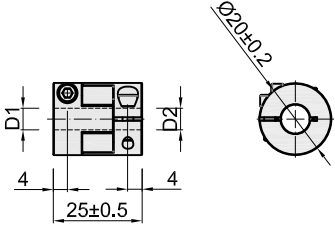
**About vibration**

Vibration act on encoder always cause wrong pulse ,
so we should pay attention to working place.
More pulse per revolution ,
narrower groovy spacing of grating ,
more effect to encoder by vibration,
when rev is low or stop ,
vibration act on shaft or main body would cause grating vibrating ,
so encoder might make wrong pulse.

S50F Specifications 6/6

■ Accessory(Need purchase additionally)

- Coupling

<p>H series spring coupling (general accuracy, or choose M series for higher accuracy) 6H8 No:8700022 8H8 No:8700023 8H10 No:8700007</p>  	Model	D1	D2
	6H8	$\varnothing 6^{+0.03}_{+0.01}$	$\varnothing 8^{+0.03}_{+0.01}$
	8H8	$\varnothing 8^{+0.03}_{+0.01}$	
	8H10		$\varnothing 10^{+0.03}_{+0.01}$
material: aluminium alloy			
<p>M series oldham coupling 6M8 No:8700038 8M8 No:8700039 8M10 No:8700040</p>  	Model	D1	D2
	6M8	$\varnothing 6^{+0.03}_{+0.01}$	$\varnothing 8^{+0.03}_{+0.01}$
	8M8	$\varnothing 8^{+0.03}_{+0.01}$	
	8M10		$\varnothing 10^{+0.03}_{+0.01}$
material: aluminium alloy			

Unit: mm

